Meteosat Third Generation (MTG): Lightning Imager and its products





Topics

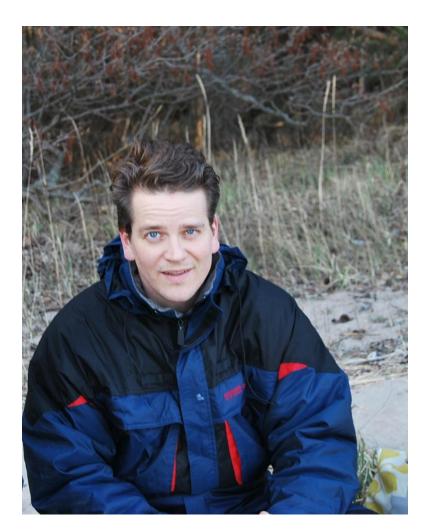
- Putting Meteosat Third Generation (MTG) into context
- Lightning monitoring from space how does the concept work
- MTG Lightning Imager
 - Design and characteristics
 - User products
- Proxy data development
- Summary



Who am I...

Jochen Grandell

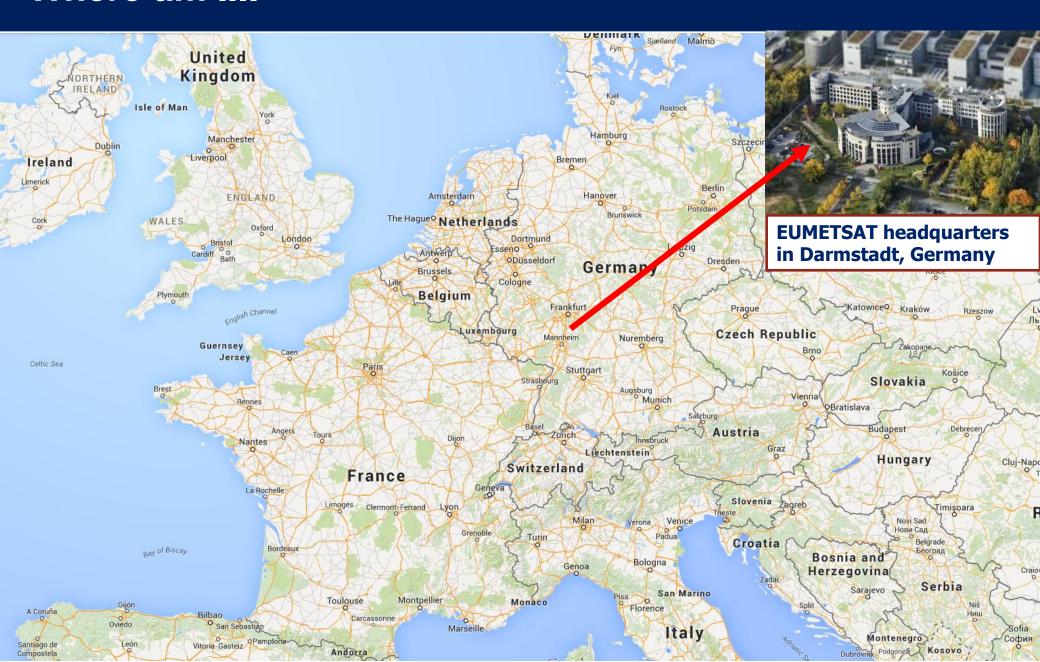
- Finnish
- With EUMETSAT since 2002
- Until very recently MTG Lightning Imager mission scientist
- Now Atmospheric and imagery applications manager



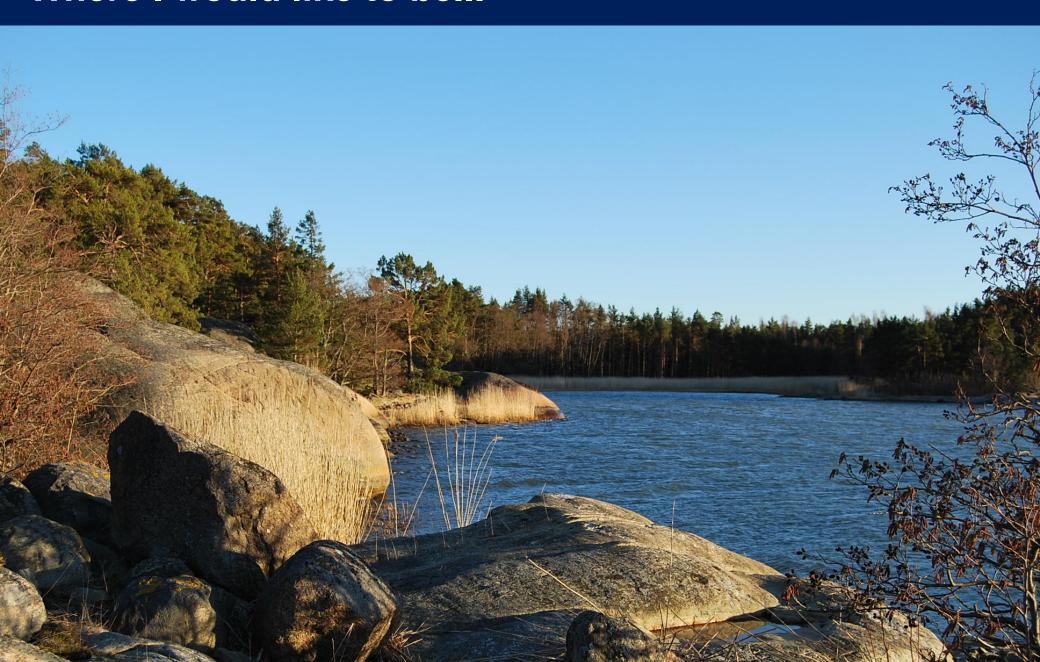
(it was cold while taking this picture...)



Where am I...



Where I would like to be...



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MTG to Secure Continuity and Evolution of EUMETSAT Services

1977 2002 2019 2021 and MOP/MTP MSG MSG MOP/MTP MTG-I and MTG-S **Observation missions:** - Flex.Comb. Imager: 16 channels **Observation missions:** - Infra-Red Sounder - SEVIRI: 12 channels Observation mission: - Lightning Imager - GERB - MVIRI: 3 channels - UVN (*) 3-axis stabilised satellites **Spinning satellite Spinning satellite** (two-satellite configuration) Class 2-ton Class 800 kg (*) Ultraviolet Visible Near-infrared spectrometer



(UVN-S4) via GMES Sentinel 4

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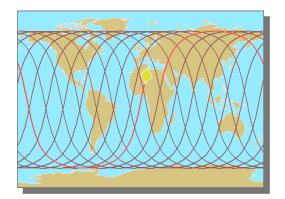
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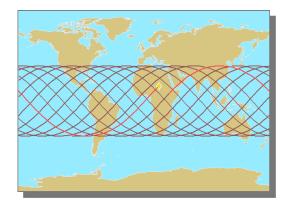
Lightning Detection from Space – from LEO to GEO

Feasibility of lightning detection from space by optical sensors has been proven by NASA instruments since 1995 on low earth orbits (LEO)

Optical Transient Detector (OTD) 1995-2000

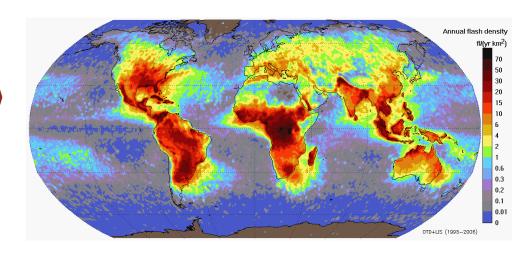


Lightning Imaging Sensor (LIS) 1997-present



Results from LIS/OTD: Global lightning distribution

Annual flash density





Geostationary lightning imaging – objectives and benefits

The LI on MTG measures Total Lightning:
Cloud-to-Cloud Lightning (IC) and Cloud-to-Ground Lightning (CG)

Main benefit from GEO
observations:
homogeneous and continuous
observations delivering
information on location and
strength of lightning flashes to
the users with a timeliness of 30
seconds



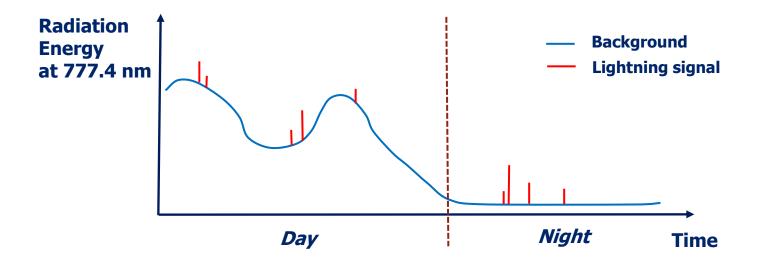
Main objectives are to detect, monitor, track and extrapolate in time:

- Development of active convective areas and storm lifecycle
- Lightning climatology
- Chemistry (NOx production)



Detection of a Lightning Optical Signal

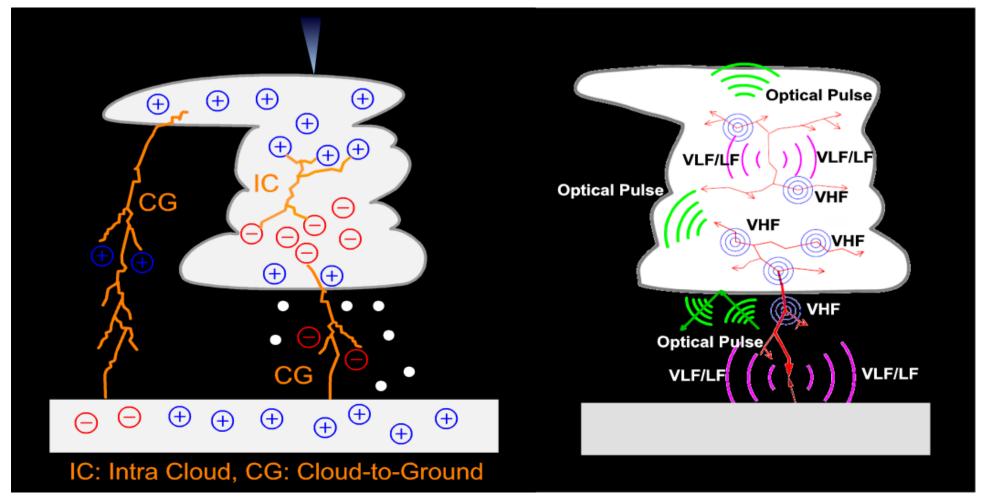
Lightning with a background signal (bright clouds) changing with time:



- Lightning is <u>not recognized by its bright radiance alone, but by its</u> <u>transient short pulse character</u> (also against a bright background)
- Variable adapting threshold has to be used for each pixel which takes into account the change in the background radiance



Thunderstorm Electrification Lightning and its Emissions



VHF – Very High Frequency,

(V)LF – (Very) Low Frequency

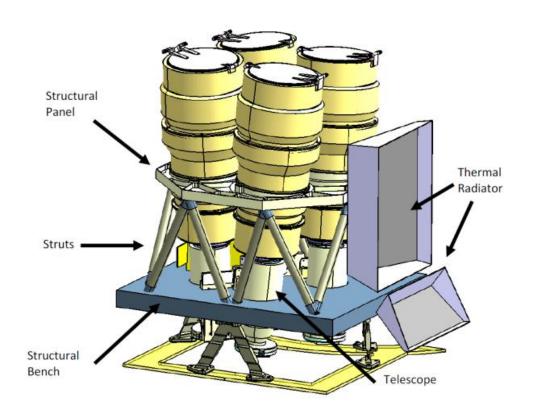


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Lightning Imager (LI) design



CMOS Back-thinned backside illuminated detectors with integrated ADCs

The baseline for the LI is a 4-camera solution

1170 x 1000 pixels per camera

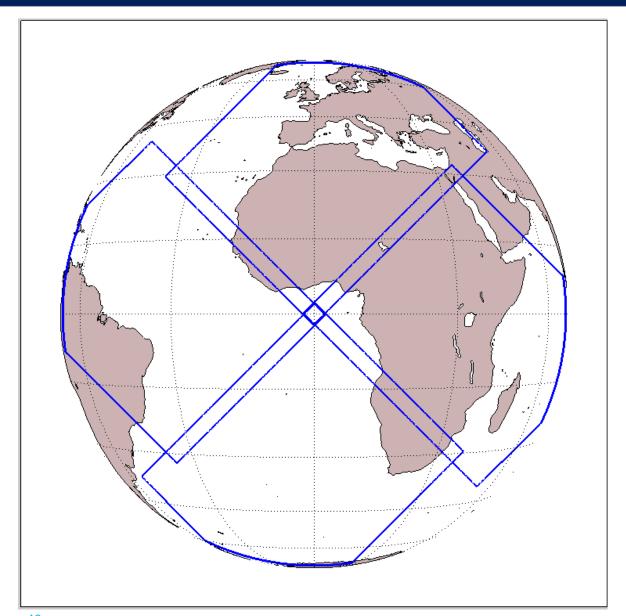


Lightning Imager (LI) – Main Characteristics

LI main characteristics:

- Measurements at 777.4 nm
- Coverage close to visible disc
- Continuous measurements of (lightning) triggered events
- Ground sample distance at sub-satellite point ~4.5 km
- Integration time per frame 1 ms
- Background subtraction and event detection in on-board electronics

LI coverage – full disk view

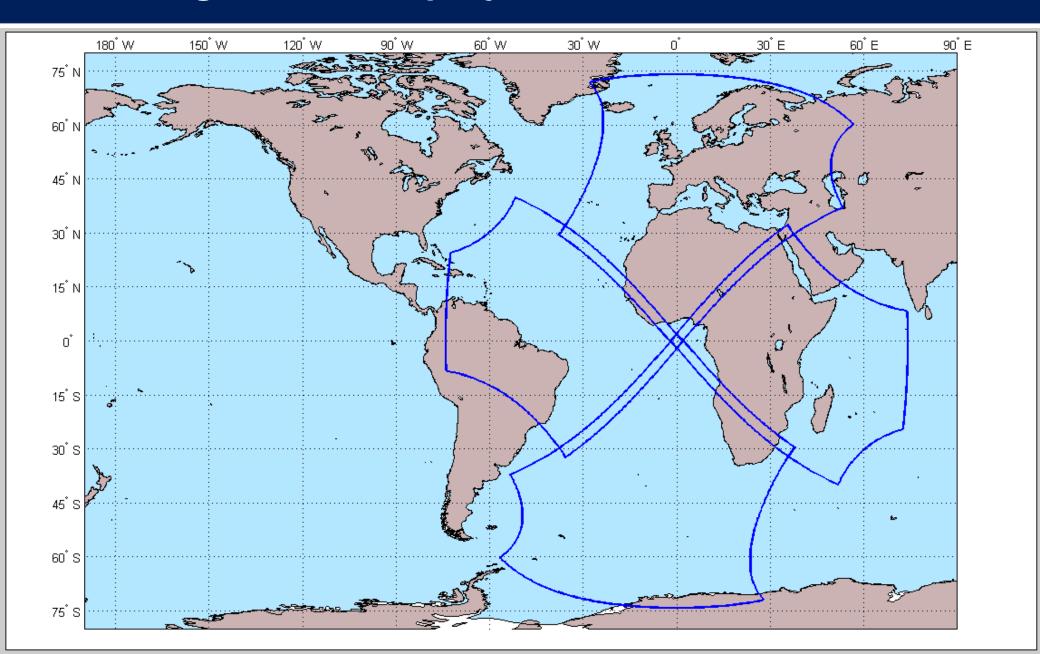


Four identical detectors with small overlaps

End-users (Level 2) will not see the "detector structure"

However, data contains information on from which detector(s) the observation is origination from

LI coverage – another projection



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Product terminology same as for LIS/GLM

- Events: what the instrument measures, a triggered pixel in the detector grid
- Groups: collection of neighbouring triggered events in the same integration period (1 ms), representing a lightning stroke in nature
- Flashes: a collection of groups in temporal and spatial vicinity (XX km, YY milliseconds), representing a "geophysical" flash.

Lightning Imager (LI) – User Products

"LI Initial Processing"

- Point data in nature in the LI grid
- Groups (strokes) & Flashes with geographical coordinates

"Accumulated products"

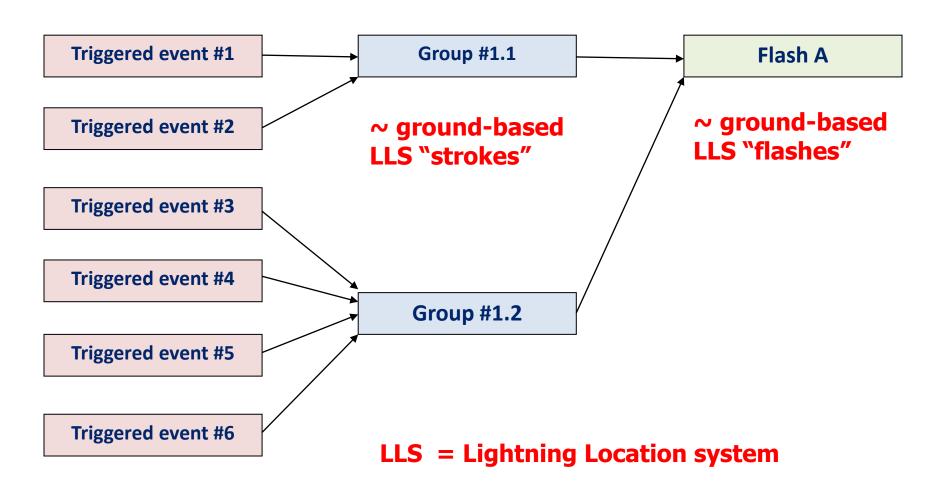
 Product density shown in the fixed MTG-FCI (*) imager grid (same grid as for the FCI IR channels in the 2 km FDHSI resolution)

(*) FCI = Flexible Combined Imager on MTG



L2 Flashes/Groups/Events

The "Flash tree" combining the events and the groups into one flash

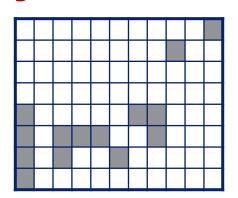


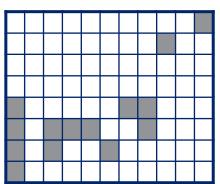
Example/Conceptual representation of a L2 processing sequence:

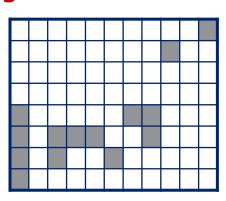
LI grid of 4.5 km at SSP

LI grid of 4.5 km at SSP

LI grid of 4.5 km at SSP





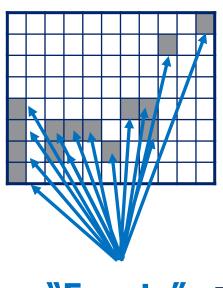


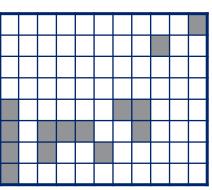
Example/Conceptual representation of a L2 processing sequence:

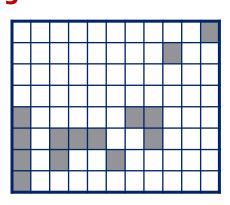




LI grid of 4.5 km at SSP



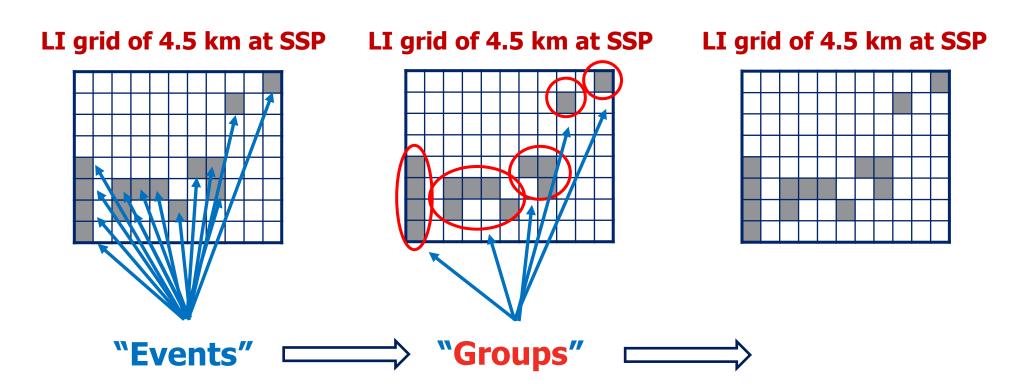




"Events" ===

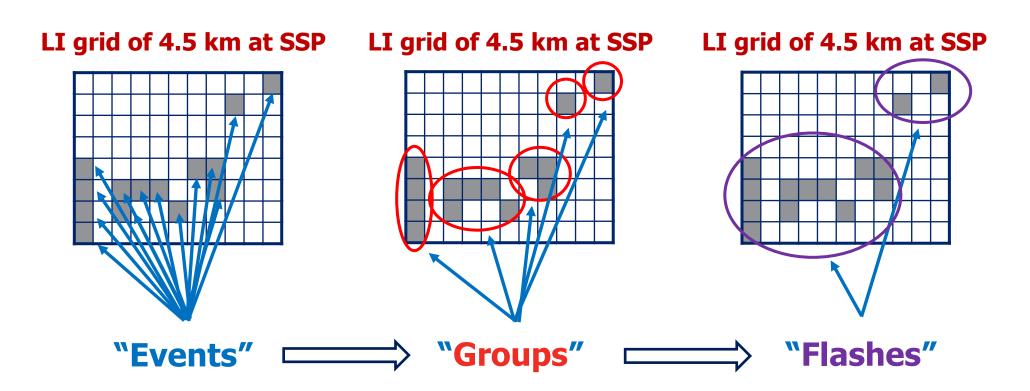


Example/Conceptual representation of a L2 processing sequence:





Example/Conceptual representation of a L2 processing sequence:





L2 Accumulated Products

- Accumulated products:
 - Collecting samples from a 30 second buffer
 - Presented in the same 2-km grid as the imager IR channel data for easier combining with imager information
 - Events define the extent in the products
 - Flashes define the values in the products
 - For a longer temporal accumulation, the 30 second products can be stacked according to users' preferences

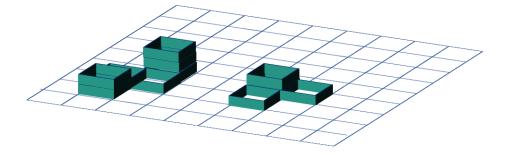
Background to accumulated products

- Current understanding has been that EUMETSAT users are mostly interested in:
 - a) Flashes
 - b) Understanding of "what kind of a flash" it is they are getting ("strength", duration, extent)
 - ⇒ Real-time users would be well served with the flashes (groups) and a supporting accumulated product coming from events
 - ⇒ The periodicity of the product should be short enough that it fits well for any further application allowing stacking of data (30 seconds)

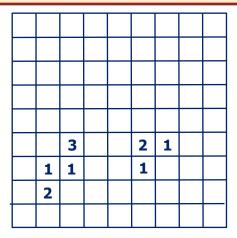


Accumulation status at t = 10s

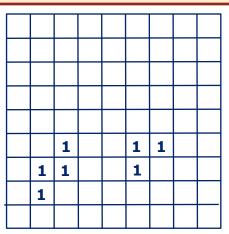




Event count in density buffer (and density grid)



Flash count in density buffer (and density grid)





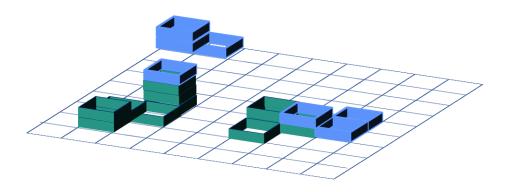
Accumulation status at t = 20s



= Events in Flash #1



= Events in Flash #2



Event count in density buffer (and density grid)

2	1						
						1	
		4		2	2	1	
	1	1		1			
	2						

Flash count in density buffer (and density grid)

1	1						
						1	
		2		1	2	1	
	1	1		1			
	1						



Accumulation status at t = 30s



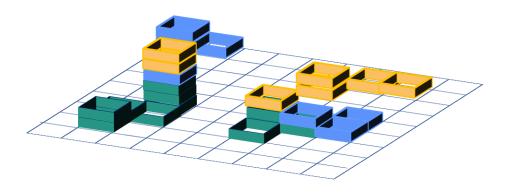
= Events in Flash #1



= Events in Flash #2



= Events in Flash #3



Event count in density buffer (and density grid)

2	1						
					1	1	
				2			
						1	
		6		3	2	1	
	1	1		1			
	2						

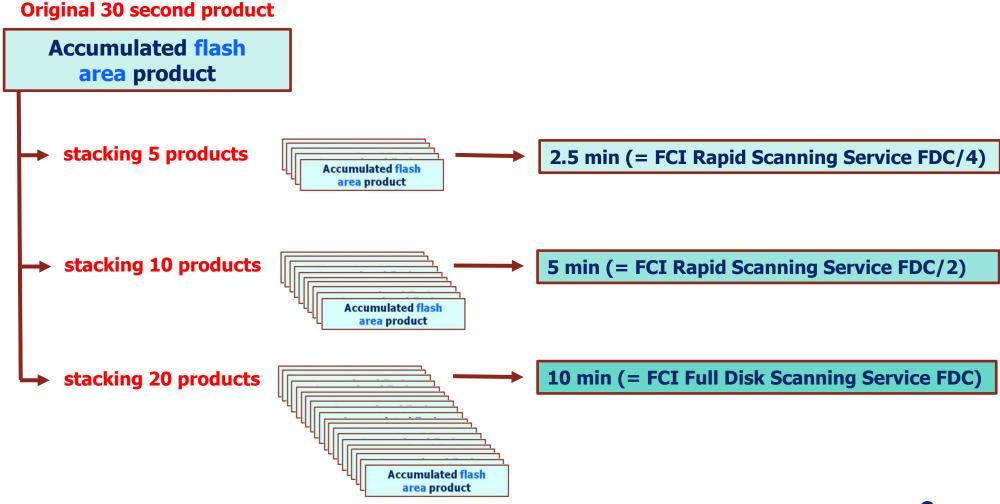
Flash count in density buffer (and density grid)

1	1						
					1	1	
				1			
						1	
		3		2	2	1	
	1	1		1			
	1						

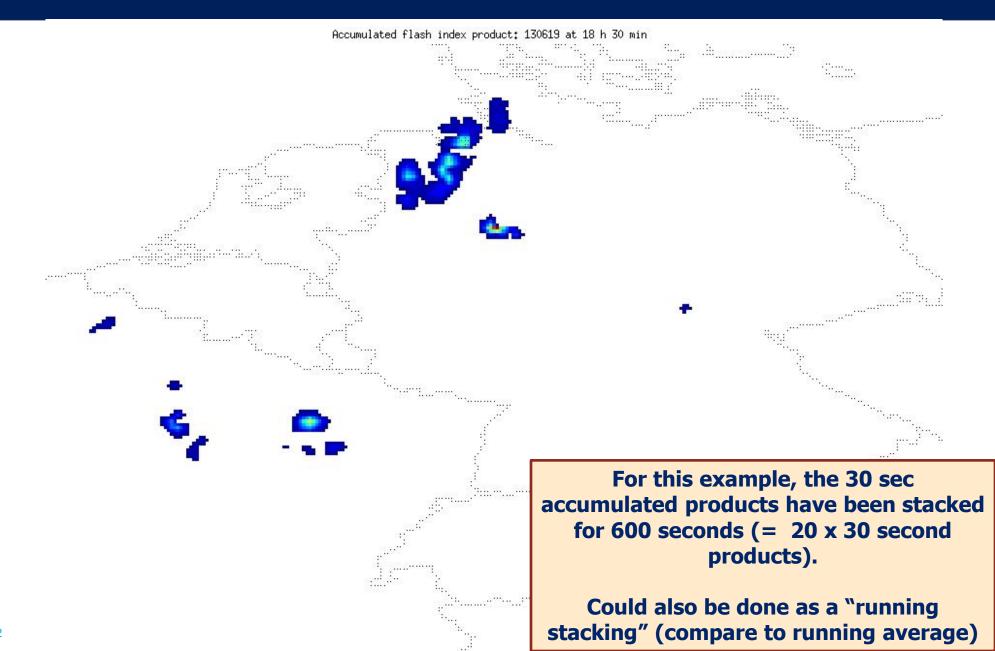


Accumulated product stacking

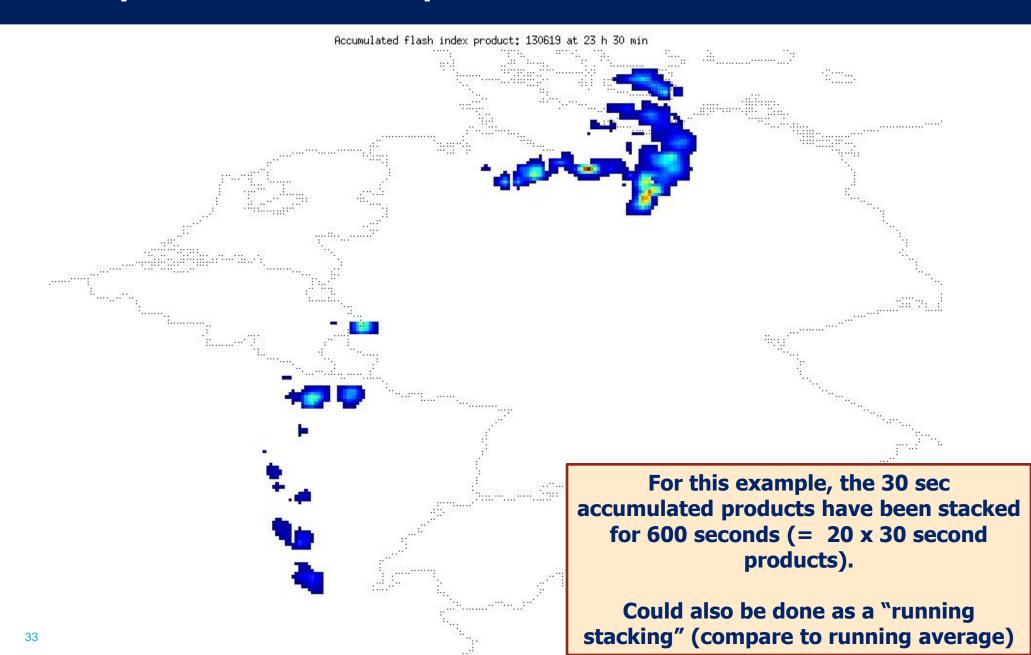
The original 30 sec product stacked into several longer time periods depending on application



Example accumulated product: 19 June 2013 at 18:30



Example accumulated product: 19 June 2013 at 23:30



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MTG LI Proxy Data – data available before launch

- MTG LI is without heritage in GEO orbit, and the closest comparison is the Lightning Imaging Sensor (LIS) on TRMM – currently still in operation
 - However, LIS flying on LEO orbit can only monitor storms for less than 2 minutes at a time (and without European coverage)
- Use of ground-based Lightning Location System (LLS) networks as a source of proxy data is not straightforward, as they are based on Radio Frequency (RF) observations of lightning and depending on the RF band (VHF, VLF, LF) they are sensitive to different parts of the lightning process
- A combination of optical + RF observations has been selected for proxy data generation



MTG LI Proxy Data – current approach

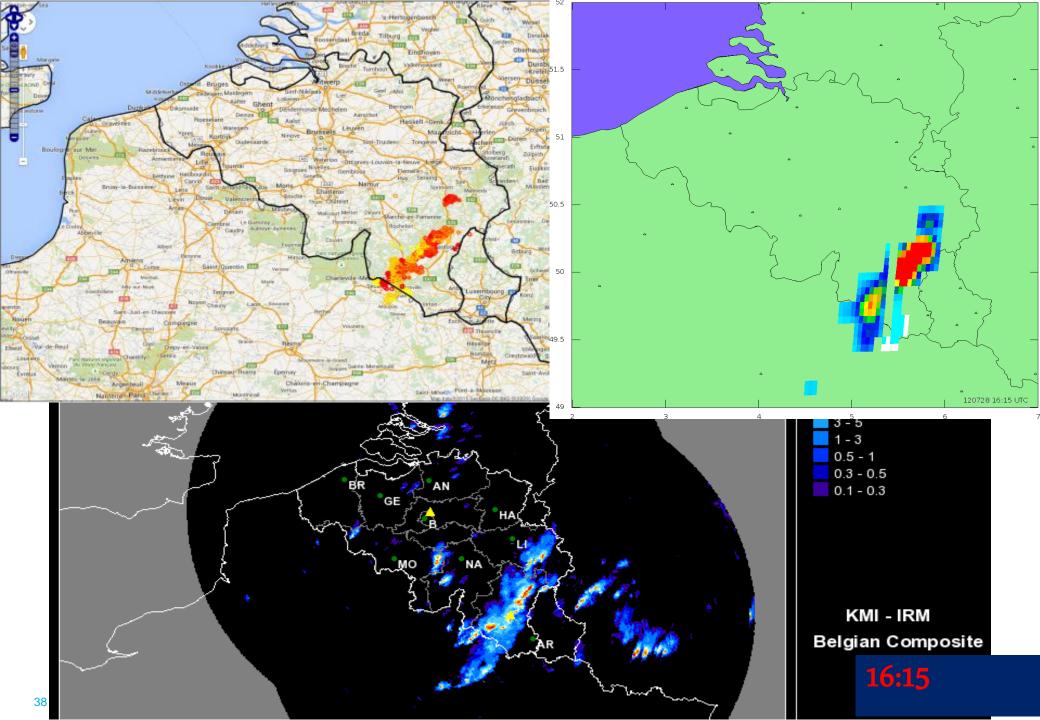
- The best compromise is to use ground-based lightning data, but converted to optical pulses based on case study comparisons with LIS data.
- One of the networks in operation in Europe (LINET) is currently the main source of such proxy data for the LI activities.
- LINET data has been compared in measurement campaigns to other ground-based systems and to LIS
- As an outcome, a model for transforming the LINET stroke data into optical emission ("pulses") has been created

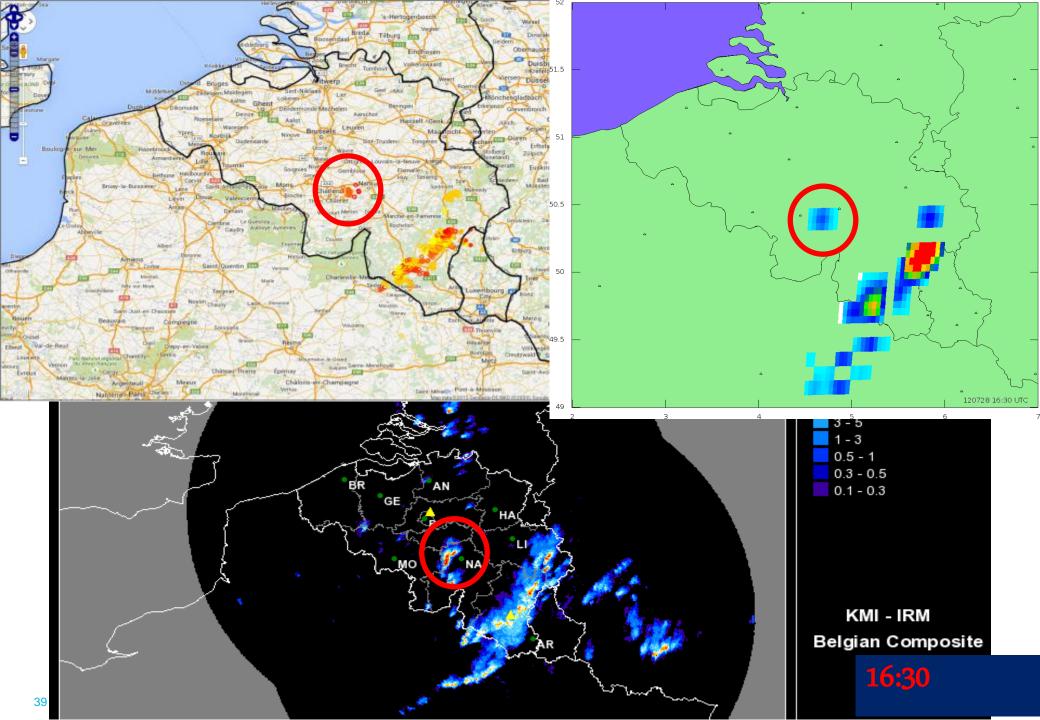


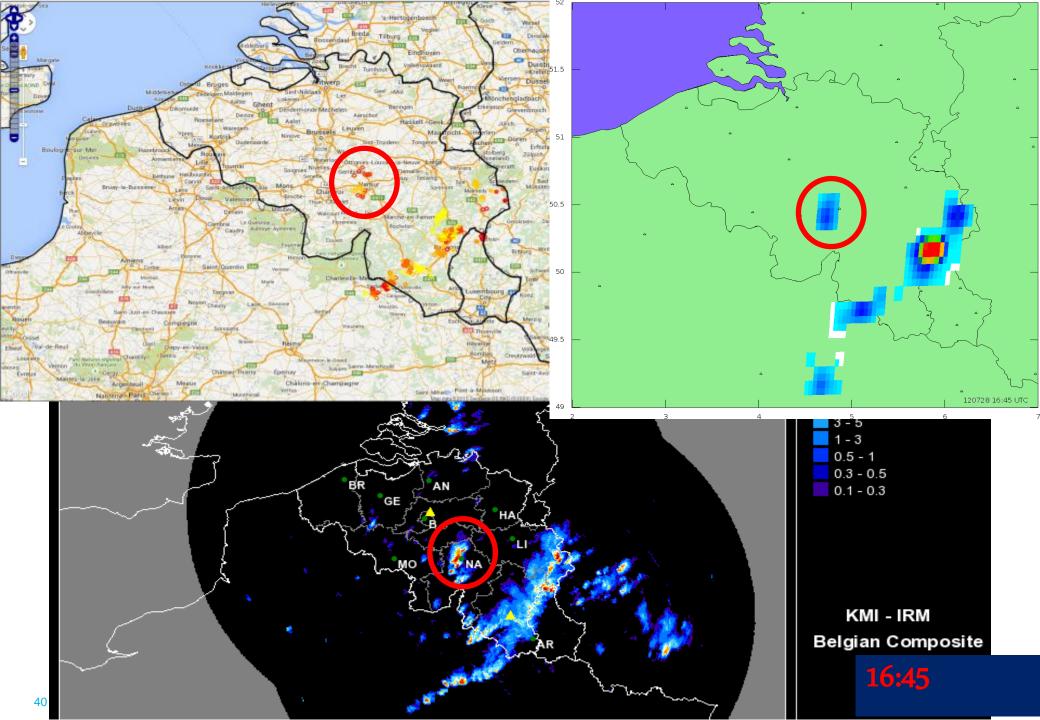
Proxy data examples

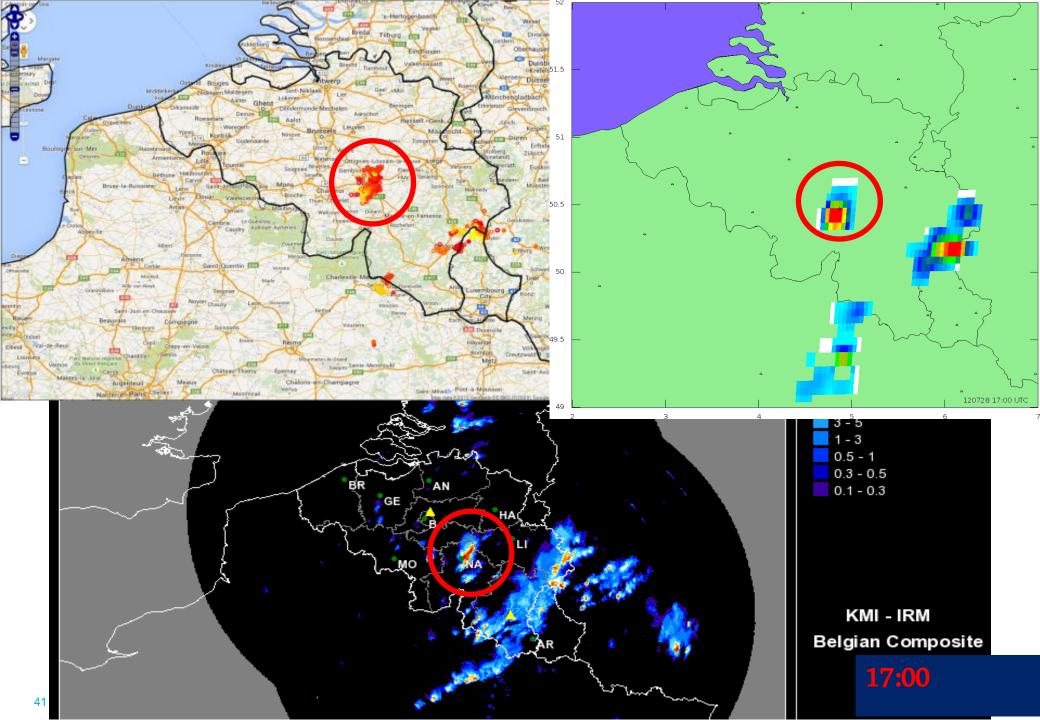
- In the following slides a comparison created by RMI (Belgium) is shown. It consists of:
- Top-right panel:
 - RMI ground-based data: combination of SAFIR and LS700x sensors placed in Belgium and also in France, Netherlands and Germany.
- Top-left panel:
 - LI proxy data (L2 accumulated product)
 - Based on LIS/LINET transformation statistics, taking into account the varying DE of LINET in the coverage area
- Bottom panel:
 - Weather radar composite

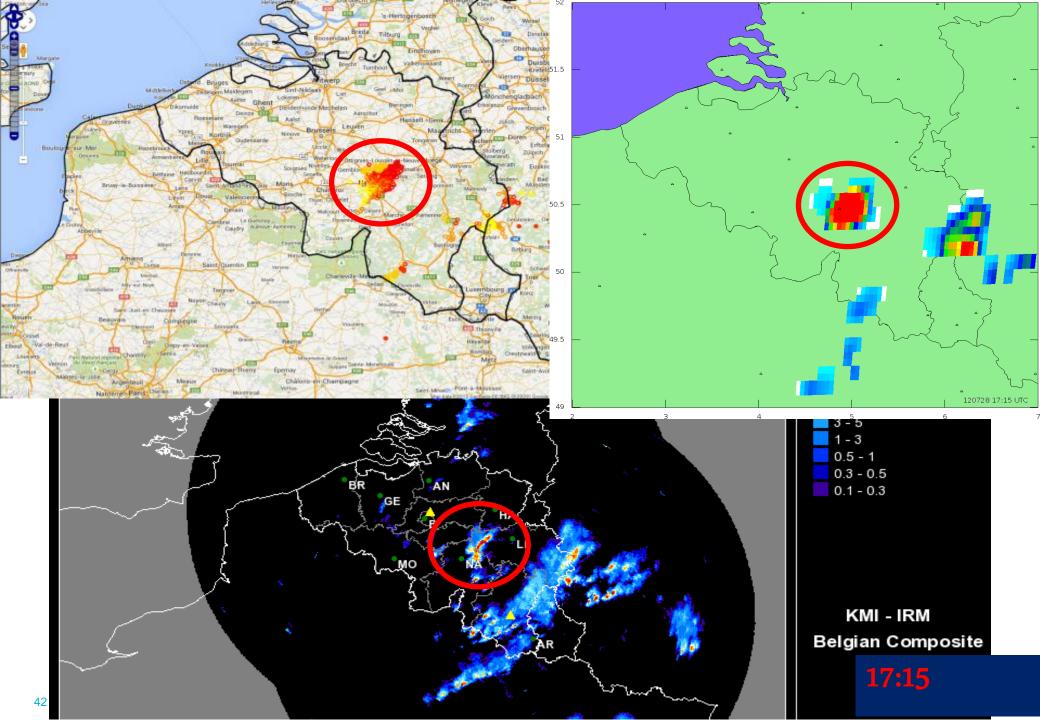


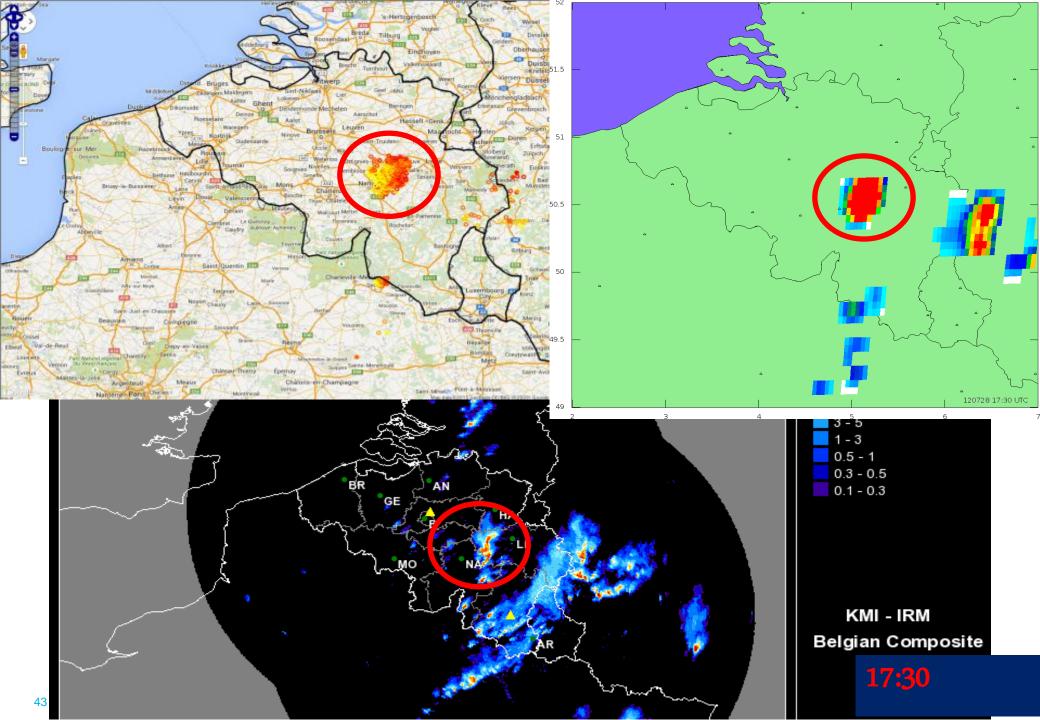


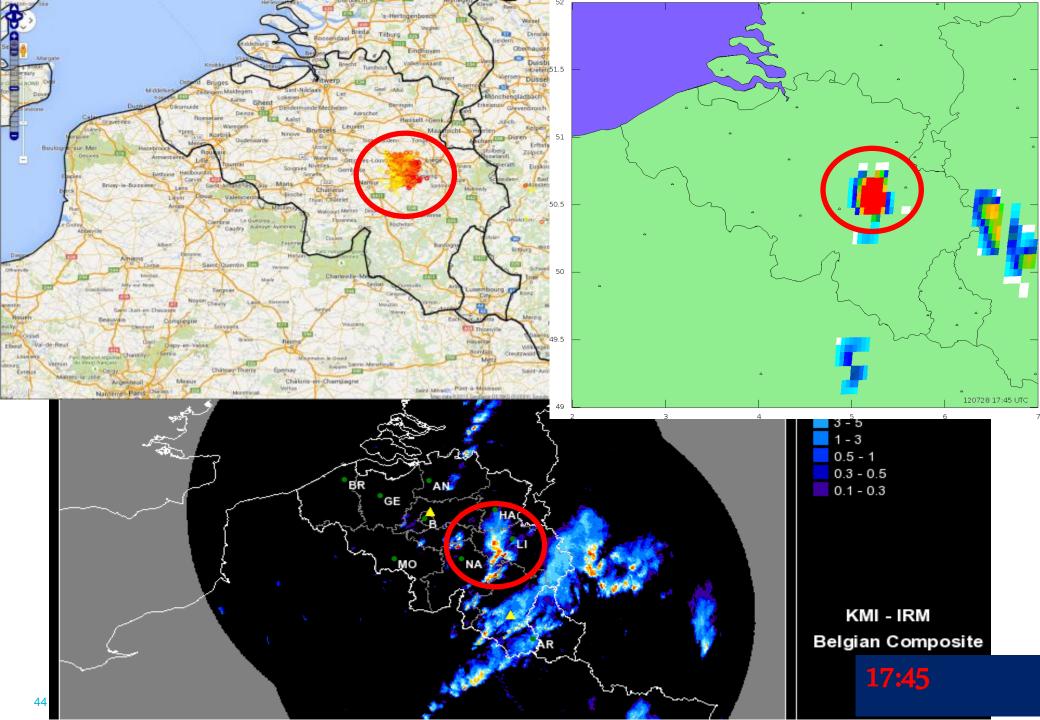


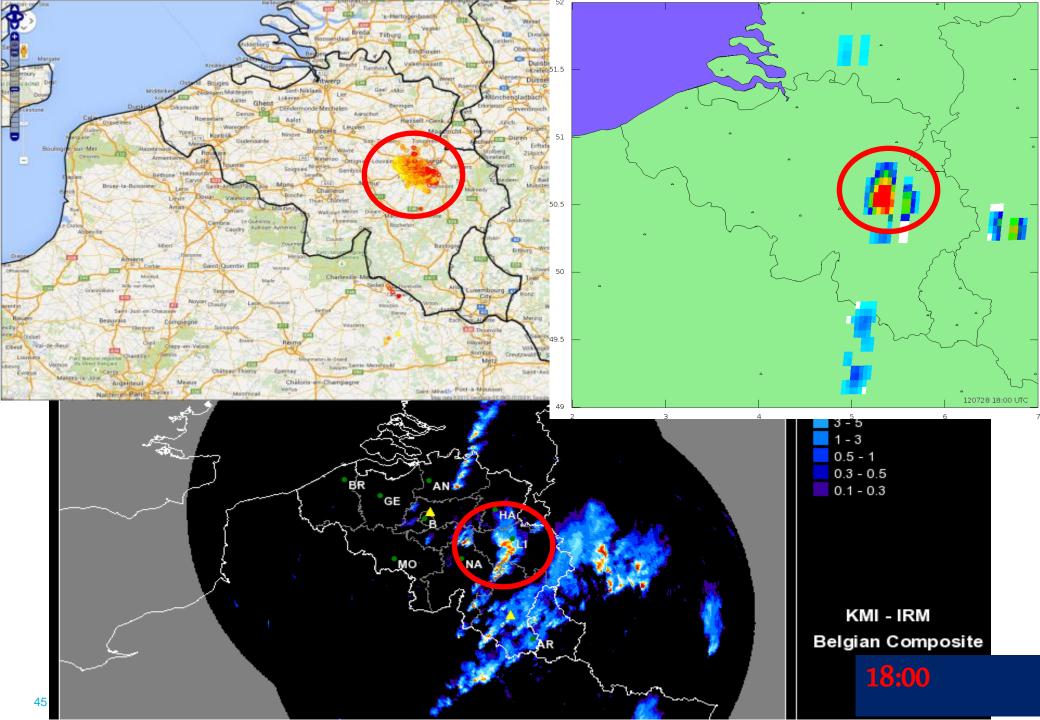


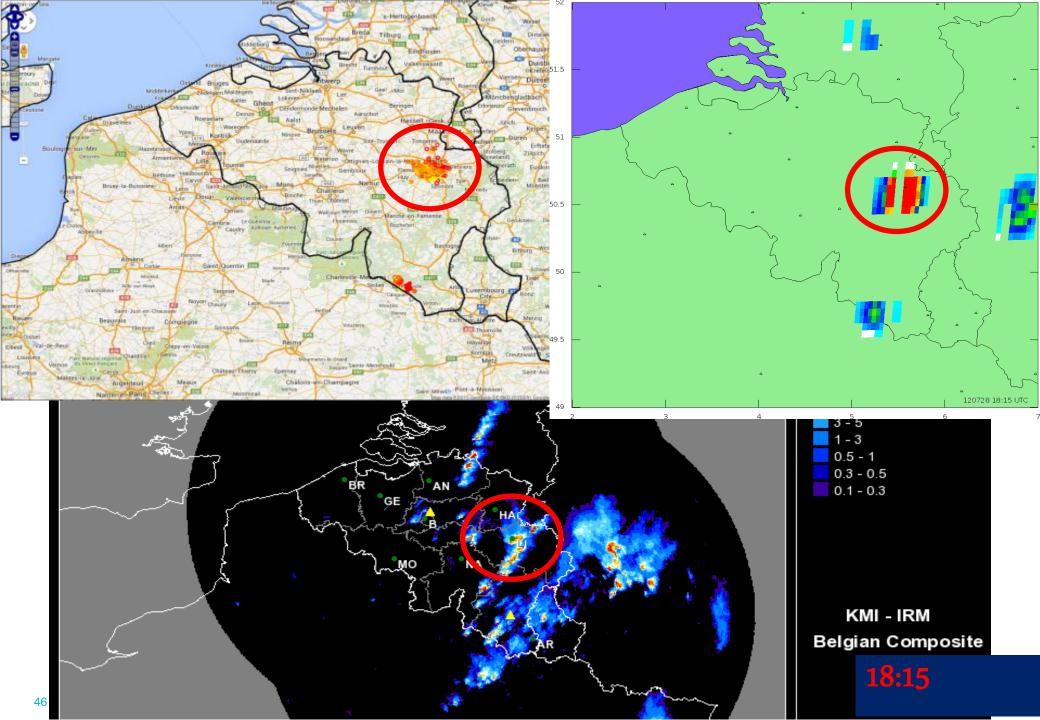


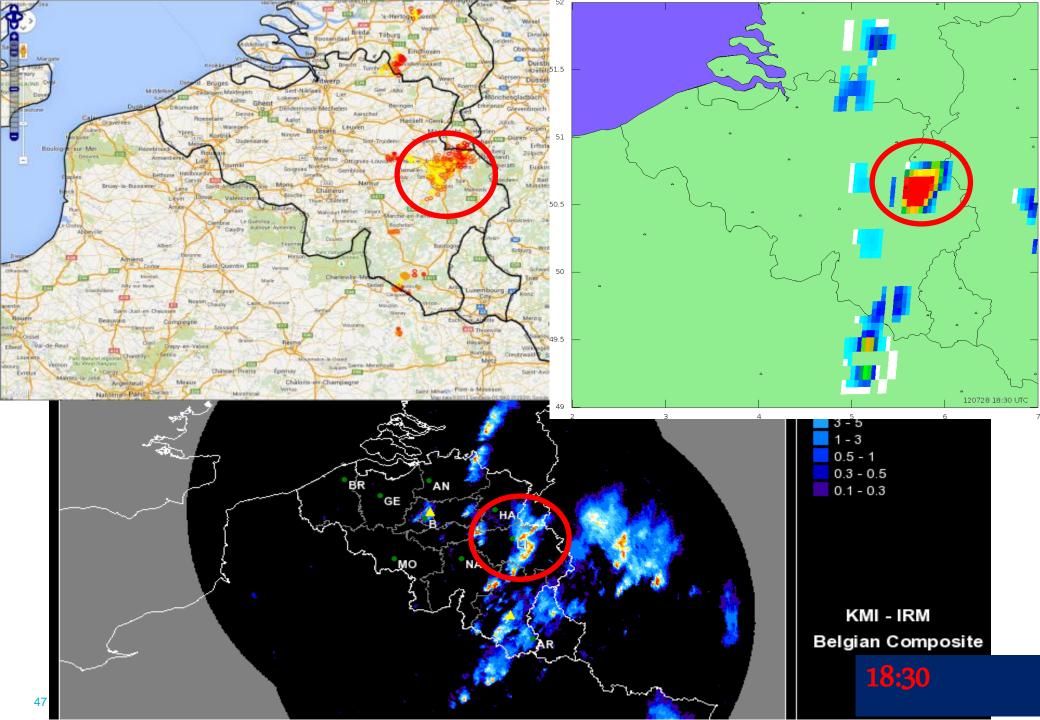


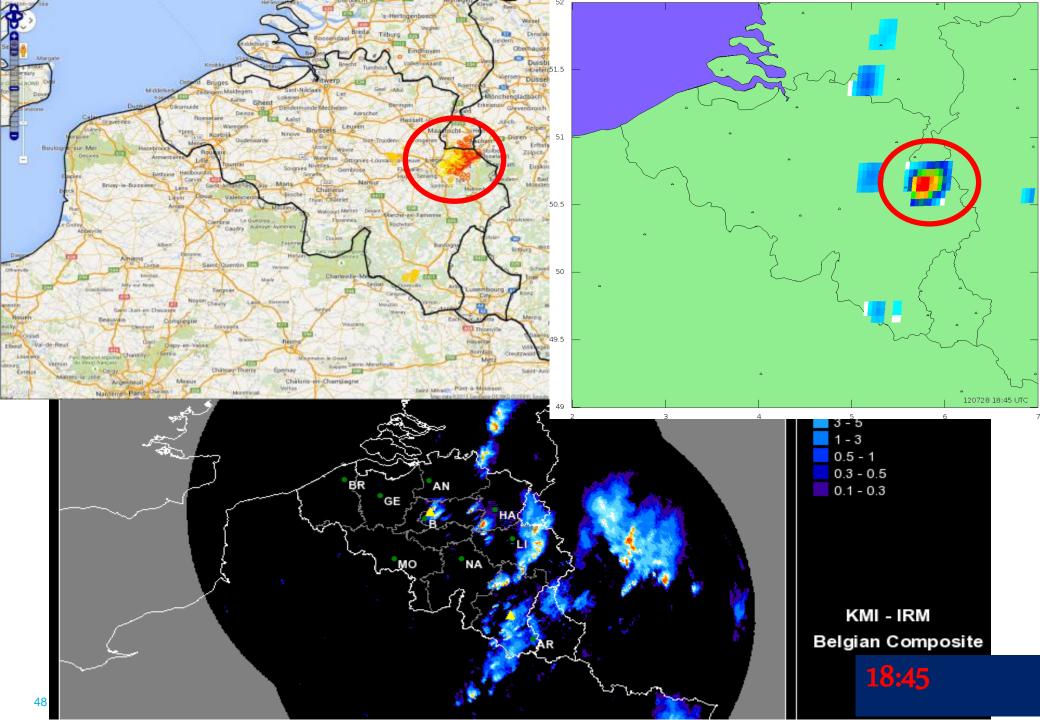


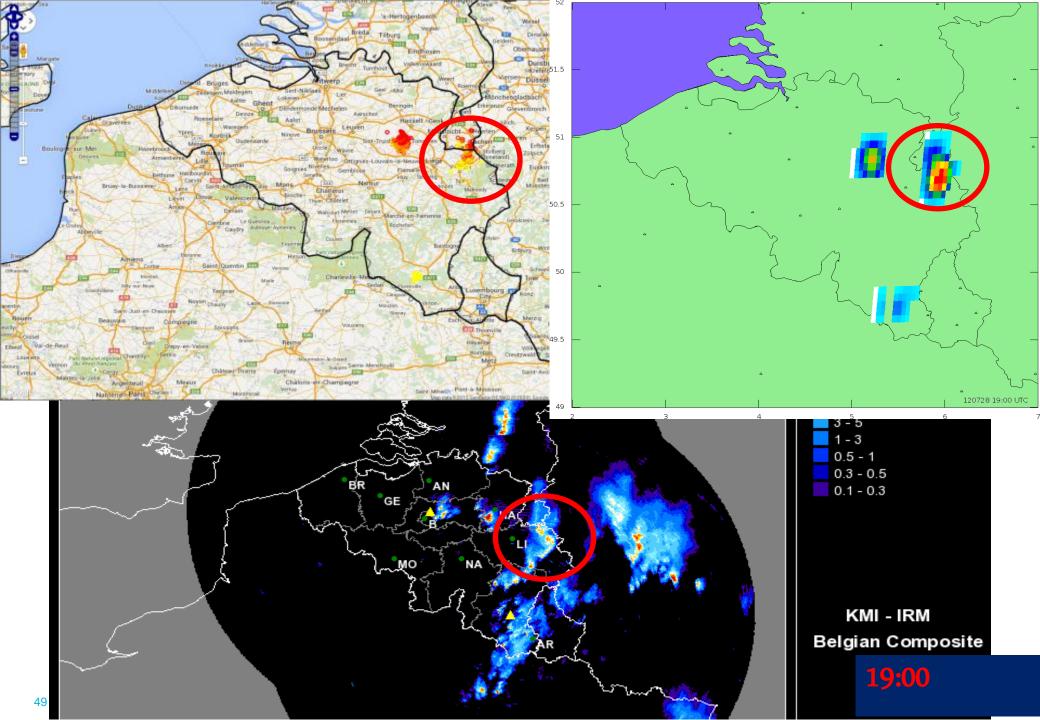


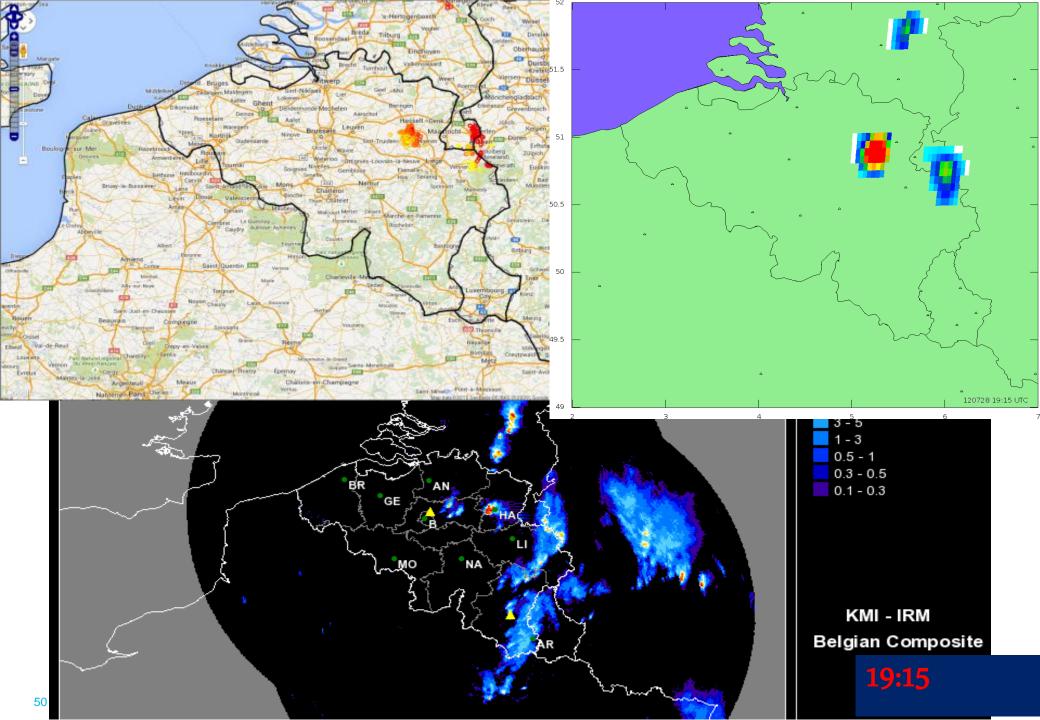


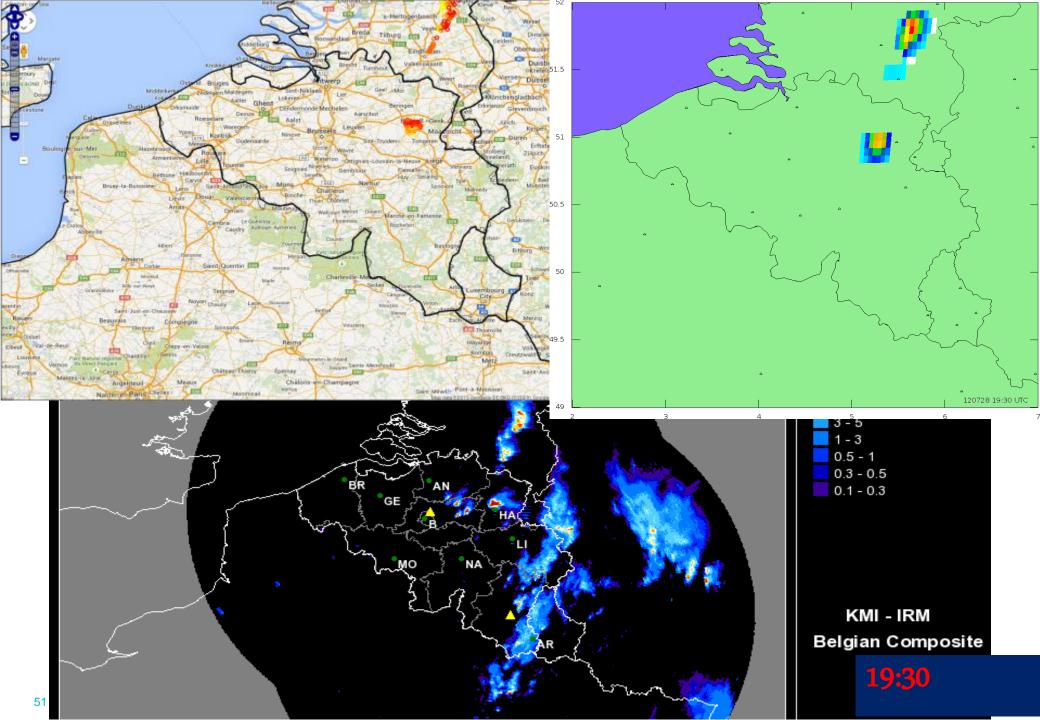












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Summary

- The Lightning Imager is a new mission on Meteosat Third Generation, with no heritage in Europe (first GEO mission will be on GOES-R in 2016)
 - (almost) Full disk coverage with 4 different detectors
 - Homogeneous and continuous observations of lightning flashes with a timeliness of 30 seconds
 - To be launched in 2019
- User products consist of
 - Initial processing data (groups and flashes)
 - Accumulated product data
- Proxy data for LI available from 2015 onwards (continuous development)

