





SAFNWC/MSG Cloud products

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Plan

 Main features + validation results for Cloud products retrieved from NWCSAF/MSG SW :

CMA cloud mask (including dust and volcanic flags)

CT cloud type (including cloud phase flag)

CTTH cloud top temperature and height

Outlook for v2015





The EUMETSAT Network of Satellite Application Facilities

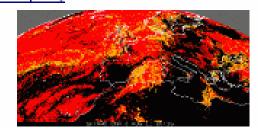




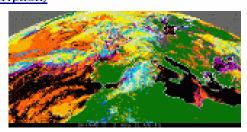
MSG

MSG Cloud Products

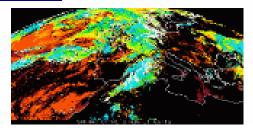
Cloud Mask (Description)



Cloud Type (Description)



Cloud Top Temperature and Height (Description)







CMA algorithm: main steps

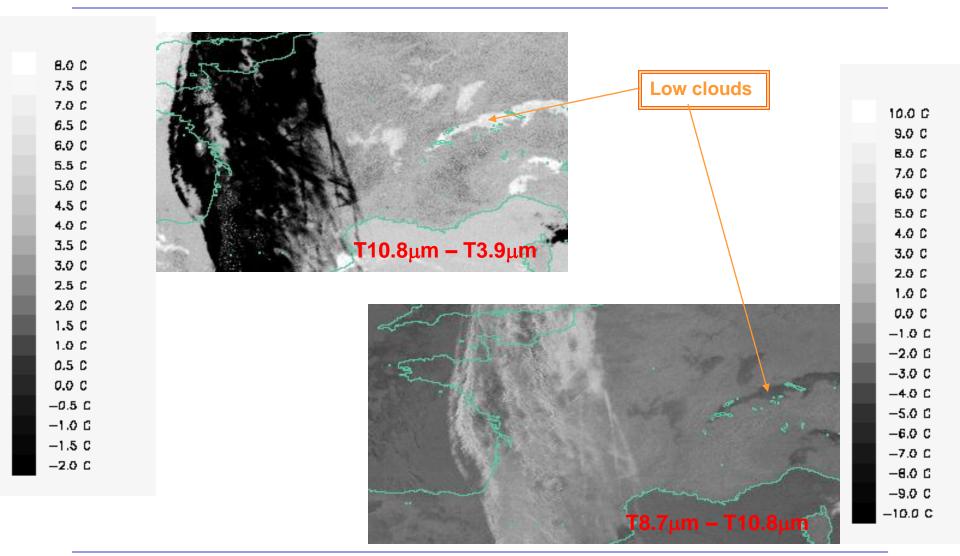
Clouds are detected in four steps:

- ✓ Multispectral thresholds (applied to each slot):
 - ✓ Channel differences are compared to thresholds supposed to correspond to cloud free conditions
 - ✓ Thresholds are tabulated using radiative transfer model in cloud free conditions (RTTOV,65)
 - ✓ Atlas and NWP fields allow to describe surface and atmosphere
- ✓ Temporal analysis: to detect thin rapidly moving clouds
- ✓ Twilight processing: to detect clouds at day-night transition and thin rapidly moving clouds
- ✓ High resolution analysis (HRV): to detect sub-pixel clouds such as cumulus



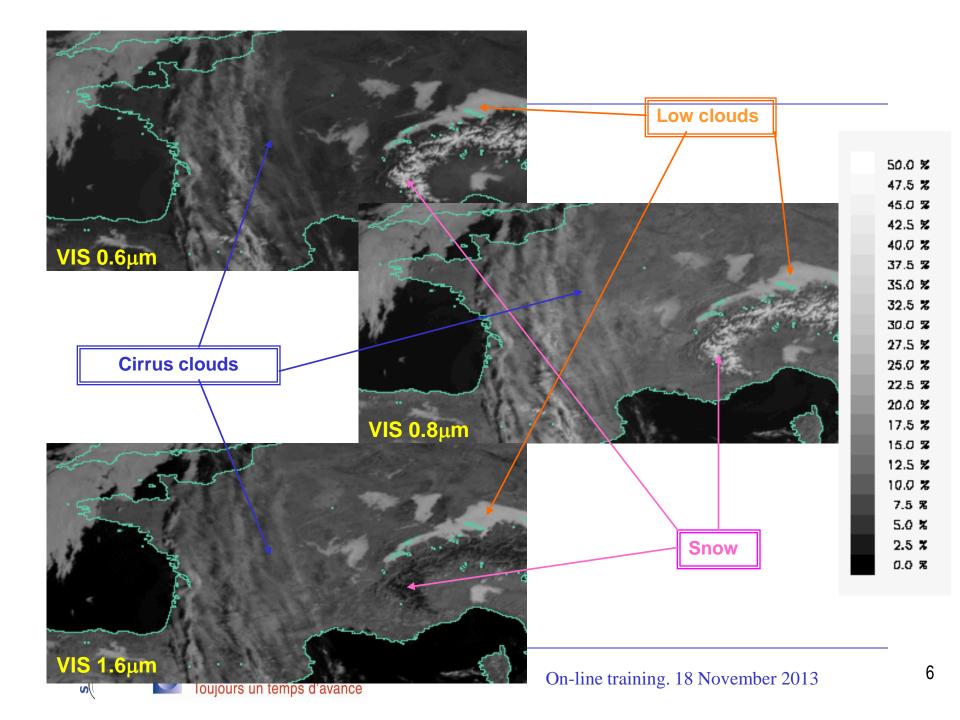


CMA algorithm: illustration of multispectral threshold

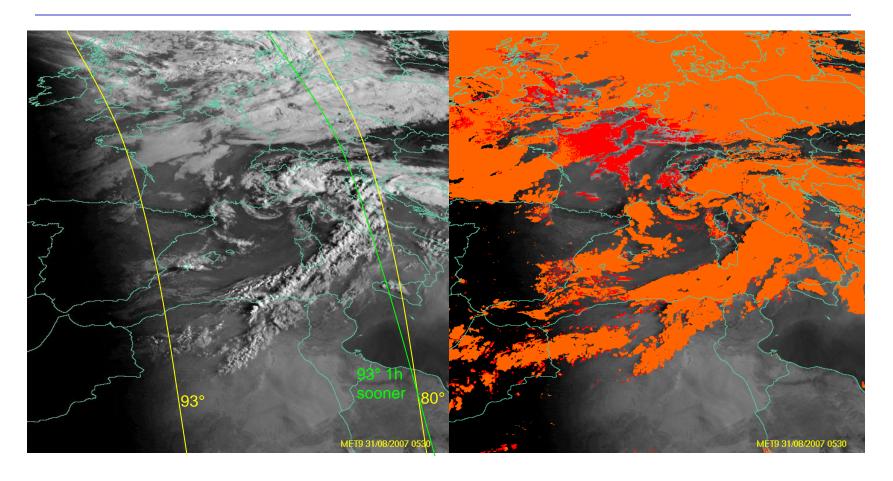








CMA algorithm: illustration of twilight processing

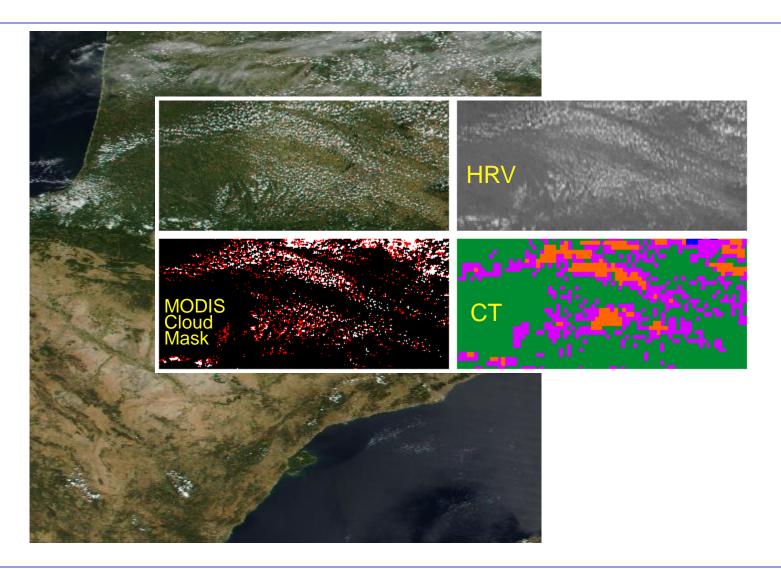


Cloud mask + temporal scheme superimposed on BRF 0.6 μm





CMA algorithm: illustration of HRV processing

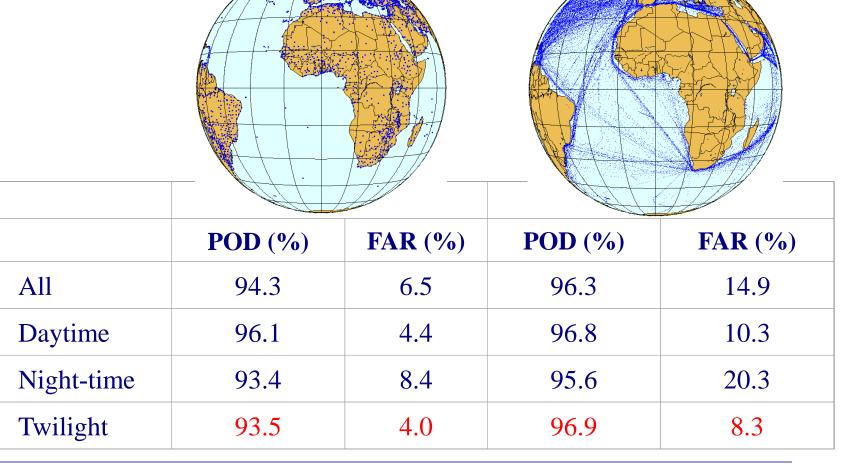






CMA algorithm: validation

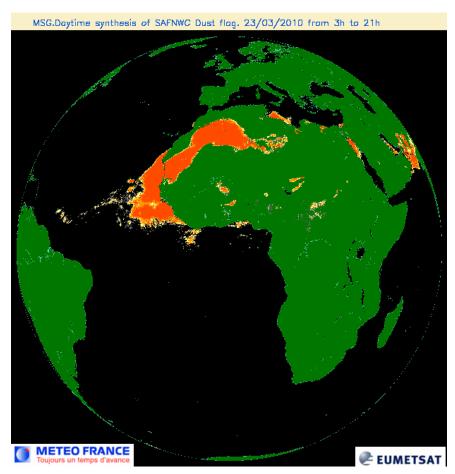
October 2009-December 2009



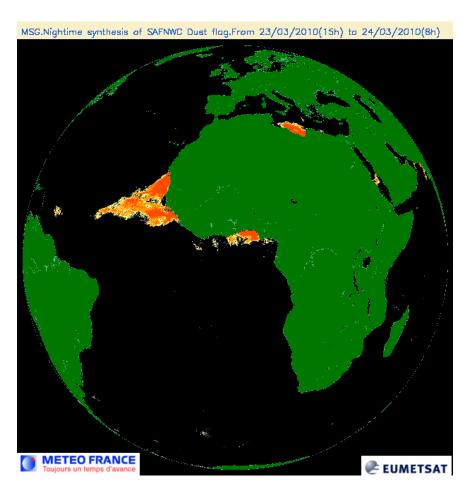




CMA algorithm: dust flag



Daytime dust flag



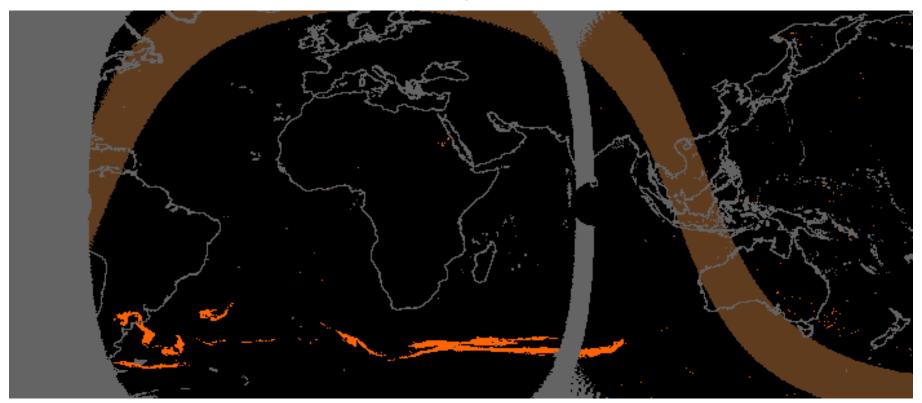
Night-time dust flag





CMA algorithm: volcanic ash (Puyehue, Chile)

June 2011







CT algorithm: main steps

Cloudy pixels are classified according their radiative characteristics:

√Semi-transparent and fractional clouds are distinguished from low/medium/high clouds using spectral features:

low T10.8μm-T12.0μm, low T8.7μm-T10.8μm
high T10.8μm-T3.9μm (night), high R0.6μm (day)

✓ Low, mid-level and high clouds are then separated by comparing their T10.8μm to combination of NWP forecast temperature at various pressure levels [850, 700, 500 hPa and at tropopause levels].





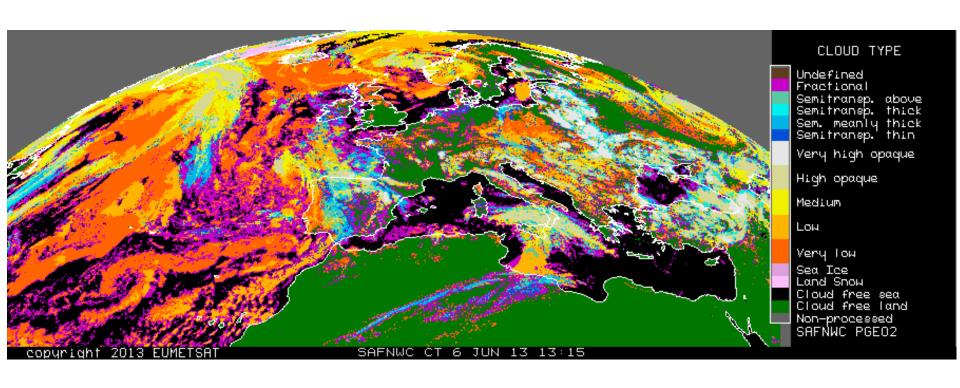
CT algorithm: low/mid-level separation

Low clouds may be wrongly classified as mid-level clouds in the presence of a thermal inversion. Two approaches are used to minimise the confusion:

- ✓ mid-level clouds are reclassified as low clouds if T10.8µmWV73µm is « large »
- ✓ mid-level clouds are reclassified as low clouds if a low level thermal inversion is detected in the NWP fields input by the user and if T8.7 μ m-T10.8 μ m is lower than a threshold (decreasing with viewing angles)



CT algorithm: exemple







CT algorithm: limitations

Stability of CT classifier to illumination (except snow)

Very thin clouds may be classified as fractional

Low clouds surmounted by thin cirrus may be classified as midlevel.





CT algorithm: cloud phase

The cloud phase identification is based on two steps: the first one is summarized in the following table:

Water clouds	Ice clouds
	Classified as high-semitransparent
	or
opaque & T10.8 > 273.15K	opaque & T10.8 < 233.15K
or	or
opaque &	opaque &
T8.7-T10.8 < thres_wat(satzen)	T8.7-T10.8 > thres_ice(satzen)

If status is still « undetermined », a second step is applied daytime: it is based on simulated cloud reflectance (at $0.6\mu m$ and $1.6\mu m$) and is illustrated next slide

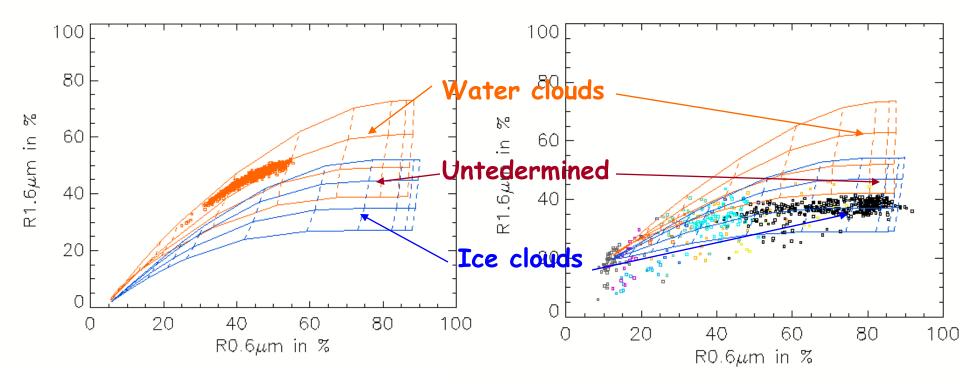




CT algorithm: cloud phase

Curves: Simulated R0.6µm and R1.6µm for 4 water clouds and 4 ice clouds.

Dots: SEVIRI RO.6µm and R1.6µm measurements



Oceanic Stratocumulus

Convective system (France)





CTTH algorithm:

- ✓ Objective: retrieve height from MSG/SEVIRI temperatures
 - -> Needed: Vertical temperature & humidity profile forecast by NWP
 - -> Computed: TOA radiances from the top of overcast opaque clouds put at various pressure levels are simulated with RTTOV





CTTH algorithm: methods

For opaque clouds (known from CT)

The cloud top pressure corresponds to the best fit between the simulated and measured 10.8 µm radiances

For semi-transparent clouds:

10.8 µm radiances contaminated by surface

-> Cloud top pressure computed from a window channel

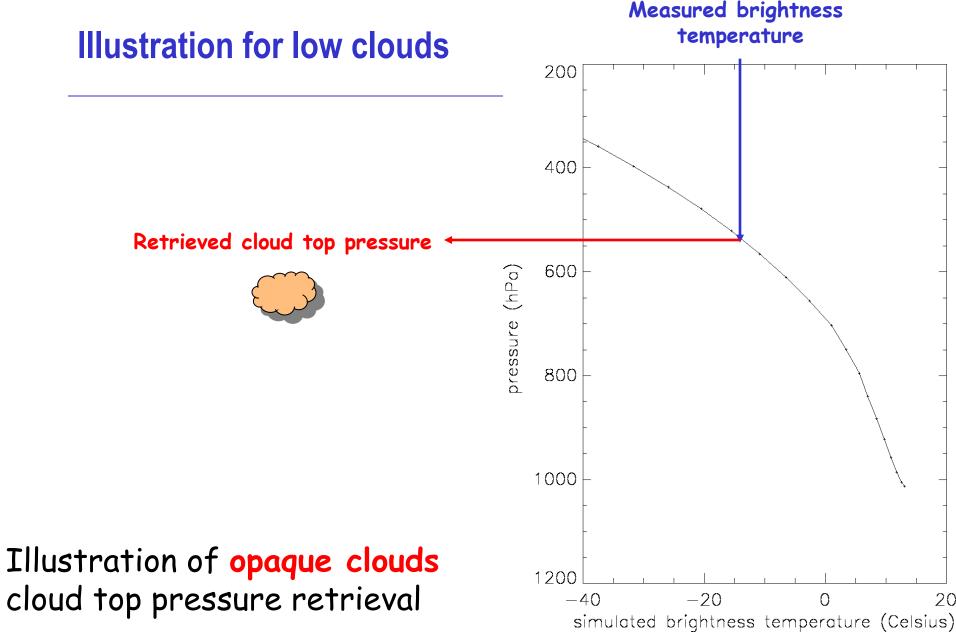
 $10.8\mu m$ and a sounding channel ($13.4\mu m$, $7.3\mu m$ or $6.2\mu m$)

For broken low clouds

No technique has been implemented.



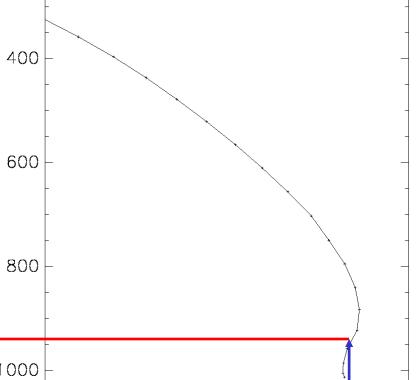












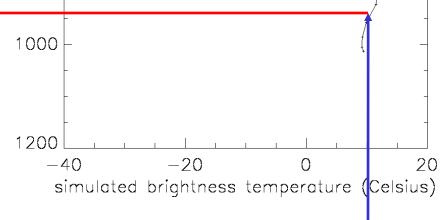
200

pressure (hPa)

Retrieved cloud top pressure



Illustration of opaque clouds cloud top pressure retrieval in case thermal inversion

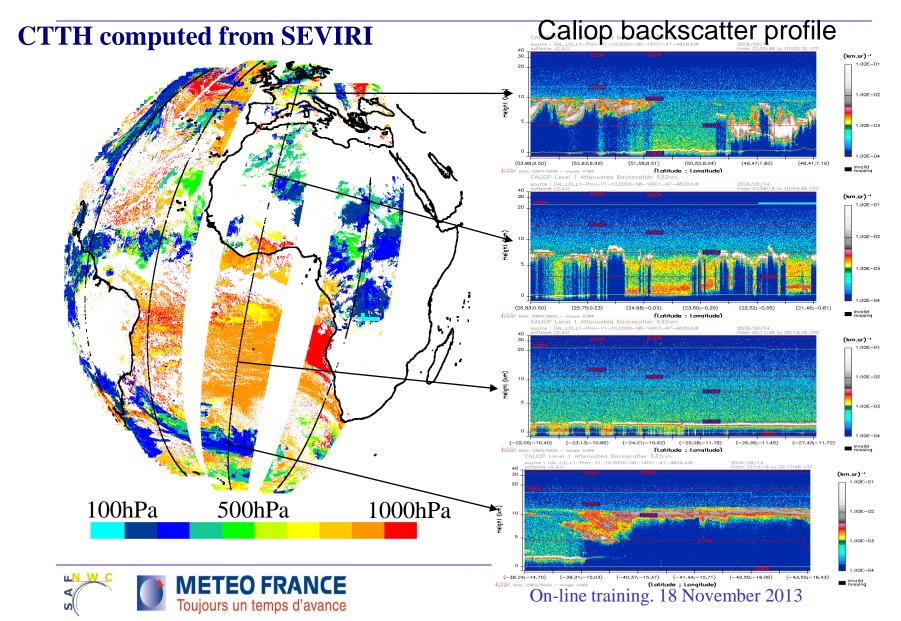


Measured brightness temperature



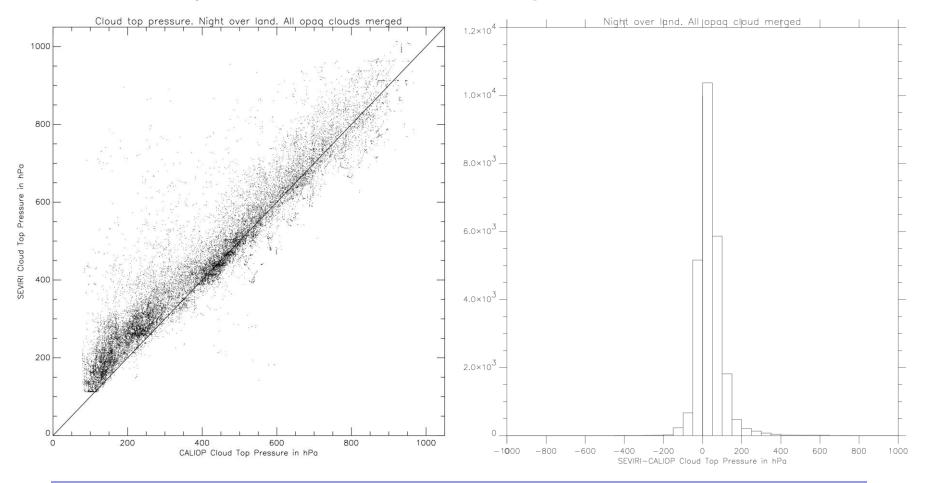


CTTH algorithm: validation with Caliop



CTTH algorithm: validation with Caliop

Opaque clouds over land in night-time conditions







Outlook for v2015

New cloud product: cloud microphysics

Use of RTTOV on-line to improve cloud detection

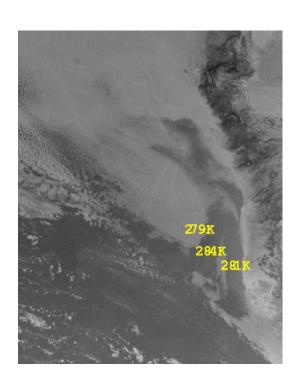
Possibility to process other geostationary meteorological satellite

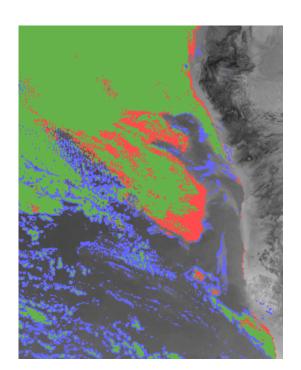


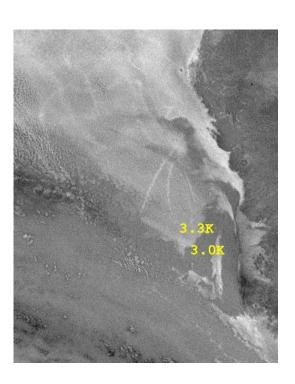


v2015: RTTOV on line to improve cloud detection

Example of Namibian/Angolan boundary layer marine stratocumulus detection







T3.9µm

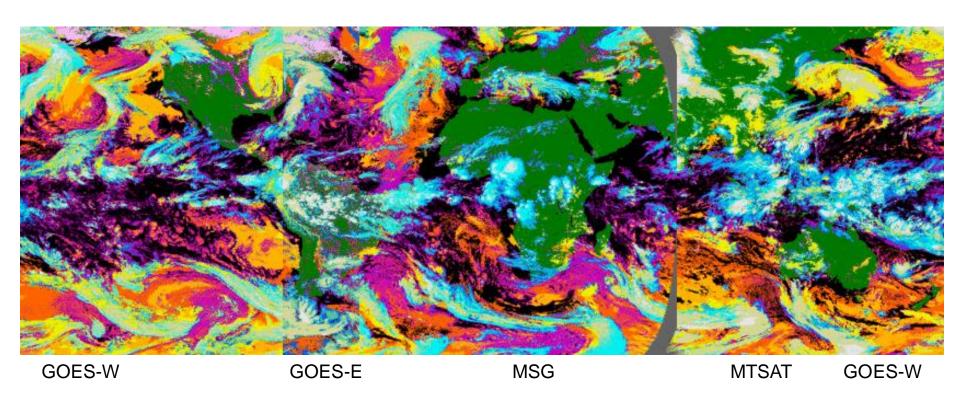
In red, improvement with RTTOV

T10.8µm-T3.9µm





V2015: process other geostationary satellites



Satellite data processed at ICARE Thematic Centre by Bruno SIX, in collaboration with Geneviève SEZE for MEGHA-TROPIQUES project, using SAFNWC package scientifically adapted by Meteo-France SAFNWC team.





v2015: New cloud microphysics products

Based on v2013 CT cloud phase algorithm

Output:

- -Cloud top phase
- -Cloud drop effective radius
- -Cloud optical thickness
- -Cloud liquid water path

Main change from v2013 algorithm in cloud simulation:

- >use of DISORT for radiative transfer model and Baum severely roughened ice particle model for ice clouds
- >use retrieved CTTH cloud top height to better account for atmosphere in cloud simulation





For more information

www.nwcsaf.org for more information



